

# Definition of Fuzzy Inference Systems based on $f$ -inclusion

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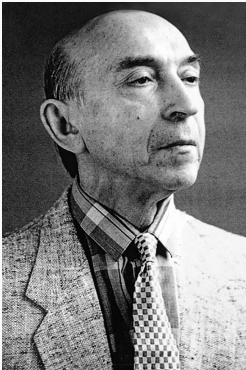
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# A brief introduction to Fuzzy Logic

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# What is Fuzzy Logic?

**Fuzzy Logic** is a branch of mathematics that was first introduced by *Lotfi A. Zadeh* in 1965.



- **Essence:** assertions are not either “true” or “false”: there is a wide range of classifications between them.
- **Objective:** to incorporate reasoning that accommodates vagueness and uncertainty.
- **Mechanism:** propositions are classified via **fuzzy sets**, which assign to objects a value in  $[0, 1]$ , where 0 stands for “false” and 1 stands for “true”.

# Definition of fuzzy set

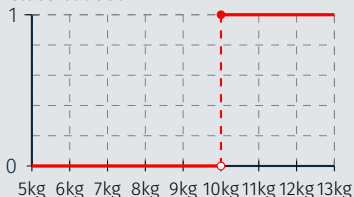
Consider the set of elements  $\mathcal{U}$  we want to classify, called **universe**. A **fuzzy set** of  $\mathcal{U}$  is a mapping

$$\begin{aligned} A: \mathcal{U} &\longrightarrow [0, 1] \\ u &\longmapsto A(u). \end{aligned}$$

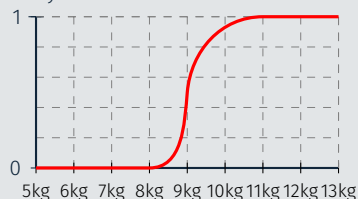
For each  $u \in \mathcal{U}$ ,  $A(u)$  is called the **membership degree** of  $u$  in  $A$ .

## Example. Fuzzy set $A$ ="Heavy laundry load"

Classical set



Fuzzy set



# Operations in Fuzzy Logic

## Operators in fuzzy logic...

- Are functions used to combine multiple fuzzy sets.
- Translate the **connectives of natural language** into a mathematical framework.
- Are used to model **inference rules**.

Name	Expression	Symbol	Formula
Conjunction	AND	$A \wedge B$	$\min\{A(x), B(x)\}$
Disjunction	OR	$A \vee B$	$\max\{A(x), B(x)\}$
Implication	IF...THEN...	$A \rightarrow B$	$\max\{1 - A(x), B(x)\}$
Negation	NOT	$\neg A$	$1 - A(x)$

# Inference Rules in Fuzzy Logic

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# Generalized Modus Ponens

Modus Ponens (MP)

$$\frac{\begin{array}{l} x \text{ is } A \rightarrow x \text{ is } B \\ t \text{ is } A \end{array}}{\therefore t \text{ is } B}$$

Example: Modus Ponens

*IF* laundry load is  $\geq 10\text{kg}$ , *THEN* wash cycle is **long**  
Laundry load is 11kg  

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 $\therefore$  Wash cycle is **long**

# Generalized Modus Ponens

Modus Ponens (MP)

$$\frac{\begin{array}{l} x \text{ is } A \rightarrow x \text{ is } B \\ t \text{ is } A \end{array}}{\therefore t \text{ is } B}$$

Generalized Modus Ponens (GMP)

$$\frac{\begin{array}{l} x \text{ is } A \rightarrow x \text{ is } B \\ t \text{ is } A' \end{array}}{\therefore t \text{ is } B'}$$

**Example: Generalized Modus Ponens**

*IF* laundry load is  $\geq 10\text{kg}$ , *THEN* wash cycle is long  
Laundry load is 9.5kg  

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 $\therefore$  Wash cycle is **medium-long**

# How can we model GMP?

To model a Generalized Modus Ponens, we need:

- A fuzzy **implication operator** to model the relation

$$x \text{ is } A \rightarrow x \text{ is } B.$$

- A **similarity function** that allows us to measure the relationship between  $A'$  and  $A$ .

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## Which operators should we use?

There exists an operator that can fulfill both roles simultaneously, and it is called...

***f*-inclusion between fuzzy sets**

## $f$ -inclusion between fuzzy sets

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# How do we measure inclusion in logic?

In classical logic, given two sets  $X$  and  $Y$ ,  $X$  is included in  $Y$  if every element that belongs to  $X$  also belongs to  $Y$ . Formally stated...

$$X \subseteq Y \text{ if and only if } \forall u (X(u) \rightarrow Y(u))$$

## Degree of inclusion between fuzzy sets

Until now, the standard inclusion between two fuzzy sets  $A$  and  $B$  has been defined as a value in the interval  $[0, 1]$  obtained from an **implication operator**.

$$S_{\rightarrow}(A, B) = \bigwedge_{u \in \mathcal{U}} (A(u) \rightarrow B(u))$$

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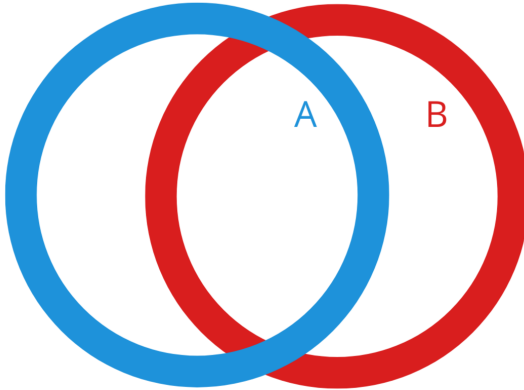
## Degree of inclusion between fuzzy sets

Until now, the standard inclusion between two fuzzy sets  $A$  and  $B$  has been defined as a value in the interval  $[0, 1]$  obtained from an implication operator.

**What if we create an implication operator from an inclusion measure?**

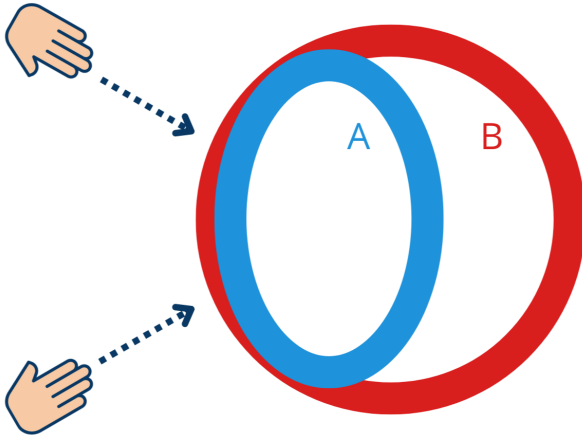
# Definition of $f$ -inclusion

An intuitive idea...



# Definition of $f$ -inclusion

An intuitive idea...



# $f$ -inclusion between fuzzy sets

## What functions can we use?

We define the **set of indexes of inclusion**  $\Omega$  as the set of functions  $f: [0, 1] \rightarrow [0, 1]$  satisfying for all  $a, b \in [0, 1]$ :

- **Increasing monotonicity:** if  $a \leq b$ , then  $f(a) \leq f(b)$ .
- **Deflation:**  $f(a) \leq a$ .

## $f$ -index of inclusion between fuzzy sets

Given two fuzzy sets  $A$  and  $B$  defined on a universe  $\mathcal{U}$  and an index of inclusion  $f \in \Omega$ ,  $A$  is said to be  **$f$ -included** in  $B$  ( $A \subseteq_f B$ ) if:

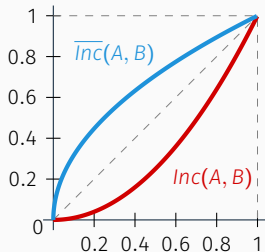
$$f(A(u)) \leq B(u) \text{ for all } u \in \mathcal{U}.$$

The  **$f$ -index of inclusion** is the greatest function satisfying  $A \subseteq_f B$ .

# GMP based on $f$ -inclusion

We denote the  $f$ -index of inclusion of  $A$  in  $B$  by  $Inc(A, B)$ . We can model a Generalized Modus Ponens:

- taking the **adjoint** ( $\overline{Inc}(A, B)$ ) of the  $f$ -indexes of inclusion involved.
- Computing their **composition**.



## Modelization of GMP

IF  $x$  is  $A$  THEN  $y$  is  $B$   $\equiv Inc(A, B)$

$x$  is  $A'$   $\equiv Inc(A', A)$

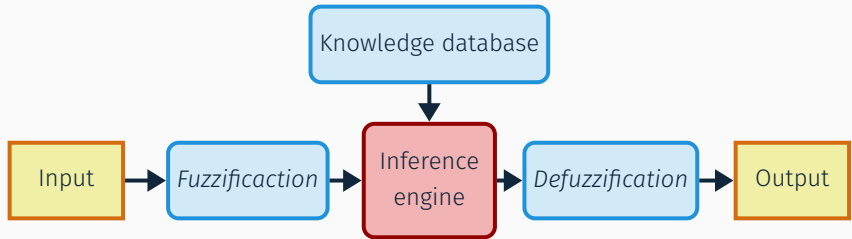
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$\therefore$   $y$  is  $B'$   $\equiv \overline{Inc}(A', A) \circ \overline{Inc}(A, B)(A')$

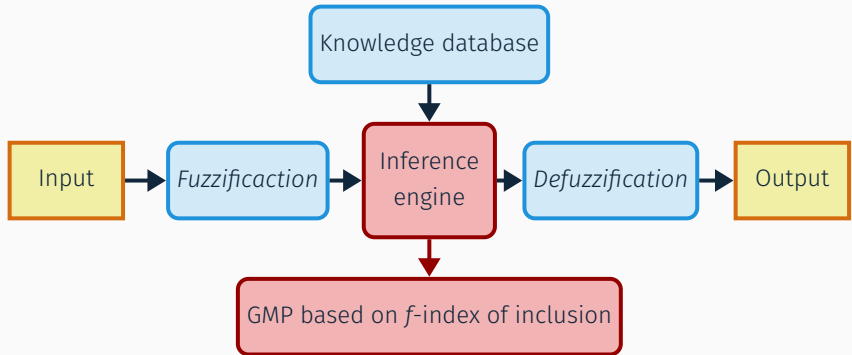
# Fuzzy Inference Systems Based on $f$ -inclusion

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# Structure of a Fuzzy Inference System



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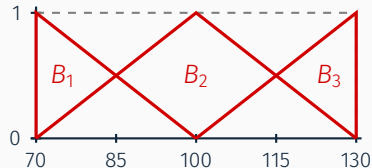
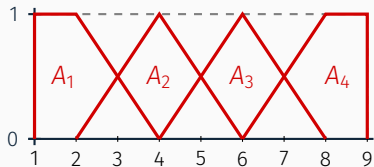


# Frame of the FIS

**Example.** Assume that we conduct a study on heart rate in infants and children between the ages of 1 and 9. We have to build a **frame** consisting of the two universes of study, which are:

- the interval  $X = [1, 9]$  representing the ages between 1 and 9.
- the interval  $Y = [70, 130]$  which covers a wide range of heart rates (in bpm).

For each universe, we build a **fuzzy partitions** which distinguish 4 different age ranges in  $X$  and 3 levels of heart rate in  $Y$ .



# Constructing the Knowledge Database (KB)

Our **KB** is composed of **rules** in the form

$$\langle A_i \rightarrow B_j ; f_{ij} \rangle,$$

where:

- $A_i$  is an fuzzy set in the partition in  $X$ ;
- $B_j$  is an fuzzy set in the partition in  $Y$ ;
- $f_{ij} \in \Omega$  is an index of inclusion.

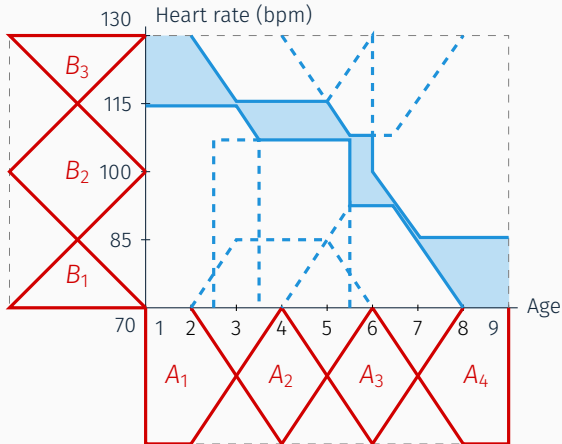
	$B_1$	$B_2$	$B_3$
$A_1$	$f_{11}$	$f_{12}$	$f_{13}$
$A_2$	$f_{21}$	$f_{22}$	$f_{23}$
$A_3$	$f_{31}$	$f_{32}$	$f_{33}$
$A_4$	$f_{41}$	$f_{42}$	$f_{43}$

## How do we interpret these rules?

The index of inclusion that appears in each rule represents the relationship between the two associated fuzzy sets. **The greater the value of the function, the stronger the relationship between them.**

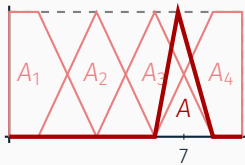
# Representation of the Knowledge Database (KB)

When we represent the **KB** on a plane, we obtain the region (shaded in blue) of data that satisfy relations indicated in the rules.

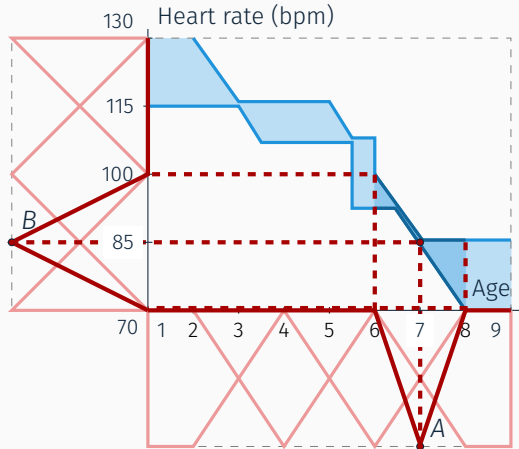


# Application of the inference engine

When we take the following input in  $X$ :



and apply the inference engine (GMP based on  $f$ -inclusion), we obtain an **output**  $B$  in the universe  $Y$ .



What have we achieved yet?

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We aim to develop a fuzzy inference system...

- With a **formal (logical) system** structure, including:
  - a syntax;
  - a semantics;
  - a definition **logical consequence**.
- With an **applied orientation**:
  - a simple theoretical structure;
  - A procedure for constructing knowledge bases from data.

# What should our FIS satisfy?

## Correctness

A FIS is **correct** if everything that can be proven (inferred) within the system is true.

## Completeness

A FIS is **complete** if everything that is true can be proven (inferred) within the system.

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## Completeness

A FIS is **complete** if everything that is true can be proven (inferred) within the system.

¡We have already proved the correctness of the FIS!

## Conclusions and Future Work

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¿What do we want to accomplish?

- We want to obtain results of **approximation of functions** with the desired accuracy.
- We want to study further procedures related to the **FIS**:
  - Fuzzification and defuzzification processes.
  - Construction of knowledge bases from data.
- ¿Would it be possible to obtain a **completeness result**?

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